

## Waste Heat Recovery of Biomass Based Industrial Boilers by Using Stirling Engine

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### ABSTRACT

Industrial boilers by using biomass for electricity generation have received significant attention recent years. However, during the process, a significant fraction of thermal energy is often lost to the environment as flue gas. The exhaust flue gas heat loss which ranges from 150-180°C has led to discovery of importance of recovering the waste heat of the flue gas to overcome the reliance on fossil fuel. Stirling engine as an external combustion engine with high efficiencies and able to use any of heat source is the best candidate to recover waste heat of the exhausted gas by converting it into power. Nevertheless, Stirling engine shows a drastic decline in performance when connected to a low temperature heat source. For this reason, CFD simulation test was performed to design an initial computational model of Stirling engine for low temperature heat waste recovery. The CFD model was validated with the experiment model and shows 4.3% of deviation. The validated model then connected to a lower temperature. It shows that when the heat source is 400K, the work done by the engine is 8.4J compared to when heat source 775K the work done is 17.0 J. The computational model can be used to evaluate method in heat transfer enhancement from low temperature heat source for low temperature waste heat recovery of biomass based industrial boilers by using Stirling engine.

### Keywords:

Waste heat recovery; Heat transfer enhancement; Stirling engine

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## 1. Introduction

As the largest palm oil producer in the world, biomass in Malaysia has an advantage over other types of renewable energy replacing coal or natural gas that give benefits in reducing carbon dioxide emissions[1]. In this process, biomass pellets are used for domestic water heating, co-firing of pulverized biomass and coal for electricity generation. For most industrial boilers using biomass, the range of thermal efficiency is 60-90%. The use of biomass to produce electricity by industrial boilers has a large fraction of thermal energy lost to the atmosphere. The temperature of the exhaust flue gas is low; usually, the temperature range is between 150-180°C [2], and it can reach up to 220°C in some case[3]. For that reason, the heat loss from the exhausted flue gas has a significant potential

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to be recovered. Recovering heat as more as possible has great impact to environmental protection and energy conservation[4].

Stirling engine with high efficiencies and quiet operation, as an external combustion engine is known for its ability to use any kind of heat source including solar, biological, geothermal, or even industrial waste heat[5] compared to steamed engines. Because of these characteristics, Stirling engine is the ideal candidate for low temperature waste heat recovery from flue gas and convert it into power[6]. Nevertheless, according to M.Bianchi *et al*[7], the performance of the Stirling engine will decrease if attached with low temperature heat sources; between 200-500°C. Therefore, study to enhance the heat transfer in the Stirling engine with low temperature heat sources should be taken into consideration.

The energy to power the Stirling engine movement is completely driven by an external source of energy, whereas energy in form of heat is added externally to the expansion chamber and removed from the compression chamber due to a differential temperature, generating work from the expansion and the compression of the working fluid[8]. Thus, the losses of heat happening during the heat transfer process in and out of the engine become important[9]. Hence, it is crucial to study methods for heat transfer enhancement for the external part of the tubular heater in order to achieve maximum efficiency of heat transfer for the best performance of the engine[10]. Earlier works have been done to study and explore the behaviour of this external heat transfer by adding different materials as heat transfer enhancement[11,12]. However, a more accurate validation is needed to strengthen the numerical result. Hence, this study is linking the gap of lacking research in studying the external part of tubular heater. Few researches have been done related to external part of the tubular heater of Stirling engine, disregarding the importance of this part in enhancing heat transfer as an external combustion engine.

Stirling engine consists of many multi-dimensional components that its geometrical effects is very important to resolved the numerical models accurately. Computational fluid dynamic (CFD) approach is one of the numerical models that can simulating the multi-dimensional components and complicate processes in Stirling engine, hence gives an accurate prediction on the overall engine performance[5]. Therefore, CFD is used to perform this study.

This work presents the study of the initial model for further improvisation for low temperature process in heat transfer from the heat source to the external part of the tubular heater of the Stirling engine. This paper, the first of two parts explains the validation of the baseline model of Stirling engine according to the previous researcher. The second part presents the validated model attached with lower temperature as low as 400K to evaluate its effect on the work done by the Stirling engine. This work is useful for further research in heat transfer enhancement in external part of Stirling engine for low temperature heat source.

## 2. Methodology

### 2.1 Governing equation

The flow field and heat transfer phenomena that happen in Stirling engine can be described mathematically by transient axisymmetric compressible Navier-Stokes equations, conservation of energy equation, conservation of mass and ideal gas equations written as;

Mass equation:

$$\frac{\partial \rho_f}{\partial t} + \frac{\partial}{\partial x}(\rho_f \tilde{u}) + \frac{1}{r} \frac{\partial}{\partial r}(\rho_f r \tilde{v}) = 0 \quad (1)$$

The momentum:

$$\begin{aligned} \frac{\partial}{\partial t}(\rho_f u) + \frac{\partial}{\partial x}(\rho_f \tilde{u}u) + \frac{1}{r} \frac{\partial}{\partial r}(\rho_f r \tilde{v}u) \\ = \rho_f g - \frac{\partial p}{\partial x} + \mu \frac{\partial}{\partial x} \left( \frac{\partial u}{\partial x} \right) + \frac{u}{r} \frac{\partial}{\partial r} \left( r \frac{\partial u}{\partial r} \right) + \frac{\mu}{3} \frac{\partial}{\partial x} (\nabla \cdot V) \\ \frac{\partial}{\partial t}(\rho_f v) + \frac{\partial}{\partial x}(\rho_f \tilde{u}v) + \frac{1}{r} \frac{\partial}{\partial r}(\rho_f r \tilde{v}v) = -\frac{\partial p}{\partial r} + \mu \frac{\partial}{\partial x} \left( \frac{\partial v}{\partial x} \right) + \frac{u}{r} \frac{\partial}{\partial r} \left( r \frac{\partial v}{\partial r} \right) \\ + \frac{\mu}{3} \frac{\partial}{\partial r} (\nabla \cdot V) - \frac{\mu v}{r^2} \end{aligned} \quad (2)$$

Energy conservation:

$$\begin{aligned} \frac{\partial}{\partial t}(\rho_f T_f) + \frac{\partial}{\partial x}(\rho_f \tilde{u}T_f) + \frac{1}{r} \frac{\partial}{\partial r}(\rho_f r \tilde{v}T_f) = -\frac{1}{c_{pf}} \left[ \frac{\partial p}{\partial t} + \nabla \cdot (pV) - p(\nabla \cdot V) \right] \\ + \frac{kf}{c_{pf}} \left[ \frac{\partial}{\partial x} \left( \frac{\partial T_f}{\partial x} \right) + \frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{\partial T_f}{\partial r} \right) \right] \\ + \frac{\mu}{c_{pf}} \left\{ 2 \left[ \left( \frac{\partial u}{\partial x} \right)^2 + \left( \frac{\partial v}{\partial r} \right)^2 + \left( \frac{v}{r} \right)^2 \right] + \left( \frac{\partial v}{\partial x} + \frac{\partial u}{\partial r} \right)^2 - \frac{2}{3} (\nabla \cdot V)^2 \right\} \end{aligned} \quad (3)$$

Ideal gas equation:

$$\rho V = \rho_f R T_f \quad (4)$$

Displacement of piston and displacer;

$$X_p(t) = L_{pt} + R_d \sin \theta + \left[ l_2^2 - \left( \frac{L}{2} - \frac{l_1}{2} - R_d \cos \theta \right)^2 \right]^{0.5} \quad (5)$$

Velocity of piston and displacer;

$$X_d(t) = L_{dt} + R_d \sin \theta + \left[ l_2^2 - \left( \frac{L}{2} - \frac{l_1}{2} - R_d \cos \theta \right)^2 \right]^{0.5} \quad (6)$$

Velocity of the piston:

$$u_p(t) = R_d \omega \left\{ \cos \theta - \sin \theta \left[ l_2^2 - \left( \frac{L}{2} - \frac{l_1}{2} - R_d \cos \theta \right)^2 \right]^{-0.5} \left[ \frac{L}{2} - \frac{l_1}{2} - R_d \cos \theta \right] \right\} \quad (7)$$

Velocity of the displacer:

$$u_d(t) = R_d \omega \left\{ \cos \theta + \sin \theta \left[ l_2^2 - \left( \frac{L}{2} - \frac{l_4}{2} - R_d \cos \theta \right)^2 \right]^{-0.5} \left[ \frac{L}{2} - \frac{l_4}{2} - R_d \cos \theta \right] \right\} \quad (8)$$

## 2.2 Modelling and Geometry

Computational fluid dynamics (CFD) modelling is used in this study. ANSYS fluent 20.1 is used to solve the continuity, momentum and energy. The wall features and thickness were detailed in the wall boundary condition to include the conduction heat transfer through external wall was solved by the software. There was very few computational works in the literature that fully provides a complete information about geometry and boundary conditions that is needed to design geometry for the CFD simulations. The computational analysis from R.Ben-Mansour *et al* [13] provides a concise information needed for the CFD simulation. Hence, his paper will be referred for the initial geometry of model of Stirling engine before adding the flue gas and heater chamber at the tubular heater of the engine.

In this study a rhombic drive mechanism  $\beta$ -type Stirling engine which consists of three zones; compression zone, expansion zone, and narrow zone as shown in Fig.1 is arrogated as an example. The narrow zone which connects the expansion and compression zone is initially assumed to have no regenerator materials. The dimensions of the geometries are stated in Table 1.

As shown in Fig.2, the simulation will be solved as 3D geometry. Air is utilized and treated as an ideal gas in this study. Air is assumed to be dependent on the gas temperature. The dimension of simulated geometry of the Stirling engine is stated in Table 1. The cylinder wall features and thickness is detailed in the wall boundary condition is as shown in Table 2. The thermal boundary conditions are limitedly between 775K for hot temperature ( $T_H$ ) and 300K for cold temperature ( $T_C$ ).

To ensure that the model is viable, further analysis on the work done by the engine is performed and compared with the experimental data of work done rfig.3eported by Aksoy[14]. The model then will be used for further evaluation with lower temperature of heat sources.

Geometry of Stirling engine used in CFD simulation is generated in Solidworks 2019. Fig. 2(b) shows physical domain of Stirling engine with outer diameter of 90 mm and height of 213.12 mm. The displacer is located 13.98 mm from the bottom surface, has diameter of 132.73 mm and height of 155 mm.

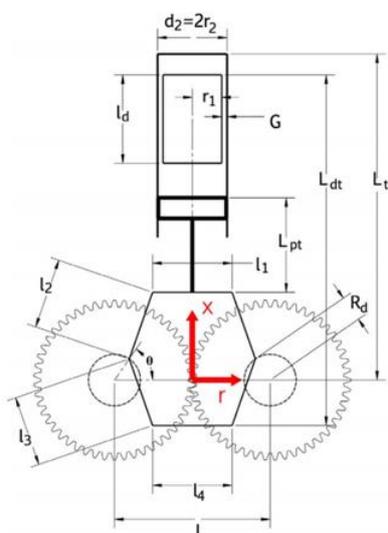


Fig. 1. Engine configuration[13]

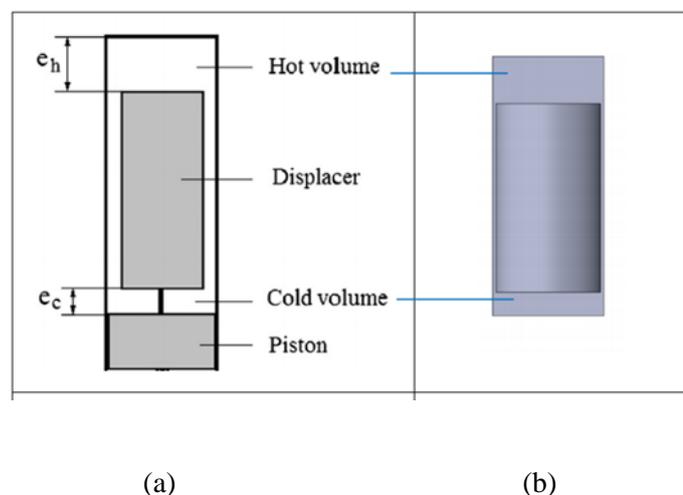


Fig. 2. (a) Schematic diagram and (b) CFD Domain

**Table 1**  
 Dimension of simulated geometry of  
 the Stirling engine in (mm)

Working fluid	Air
$r_1$	43
$r_2$	42.25
$l_d$	155
$l_1 = l_2 = l_3 = l_4$	66
$R_d$ (mm)	$l_1/2.6666$
$L_{pt}$	50.93
$L_{dt}$	163.74
$R_d$	3.5
Engine speed	500rpm

**Table 2**  
 Cylinder wall dimensions and properties

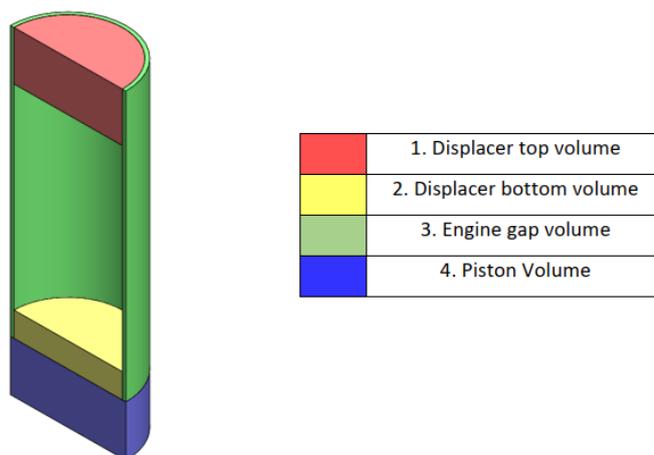
Thickness (mm)	1
Material	Steel
Density ( $\text{kg/m}^3$ )	7840
Thermal conductivity ( $\text{Wm}^{-1} \cdot \text{k}^{-1}$ )	43
Specific heat ( $\text{J} \cdot \text{kg}^{-1} \cdot \text{K}^{-1}$ )	450

### 2.3 Mesh and Boundary condition setup

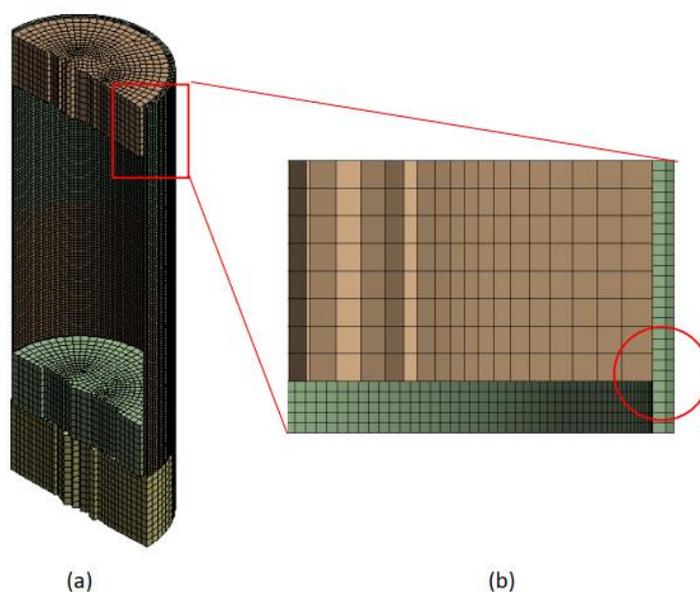
To simplify the analysis, the Stirling engine domain is divided into four volumes, namely as displacer top volume, displacer bottom volume, engine gap volume and piston volume as shown in Fig.3. It is also divided into four sub-domains (volumes) to have a better control of mesh generated to reduce number of element and reduce computational time. The generated geometry is exported into Parasolid format (.x\_t) to be imported into ANSYS Design modeler.

The user-defined function (UDF) and dynamic mesh is applied for the movement of the piston and displacer at transient condition. Layering mesh method is used in dynamic mesh function. Air is utilized as working fluid and set as the ideal gas. The thermal boundary condition was shown at 775K for the heating surface and 300K for the piston surface for the validation model, and the heating surface is changed to heat source 600K, 500K and 400K for lower temperature analysis. The analysis is pressure based with unsteady RANS(URANS). Analysis performed with Energy model turned on with k-omega SST turbulence model. The equations then were discretized with the Coupled scheme Pressure-velocity coupling algorithm because it shows a relatively fast convergence compared to SIMPLE scheme [8]. The second-order upwind scheme is used for the density, momentum and energy equations while the first-order upwind scheme is used for the turbulent kinetic energy and specific dissipation rate.

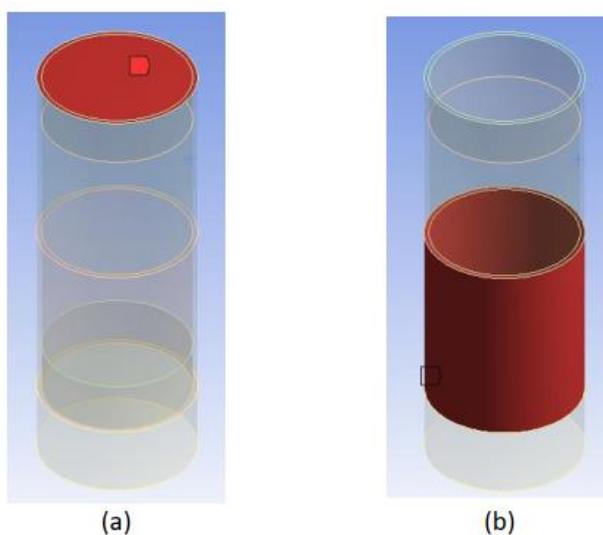
Fig. 4 (a) shows overall mesh in this study, with minimum and maximum element size are 1.5mm and 2.5mm, respectively. All the mesh generated using structured mesh with combination of hexahedral and quadrilateral 3D elements with total element number of 87,882. Fig. 4 (b) shows mesh at the gap between displacer and engine gap with element size of 2.5 mm. Temperature source defined in boundary condition as shown in Fig. 5 for (a)cold surface and (b)hot surface.



**Fig. 3.** Four volume of Stirling engine generated in crosscut at mid-plane



**Fig. 4.** Mesh generated for this study (a) overall mesh (b) refined mesh at the engine gap



**Fig. 5.** Two boundary condition for heat source (a) hot surface and (b) cold source surface

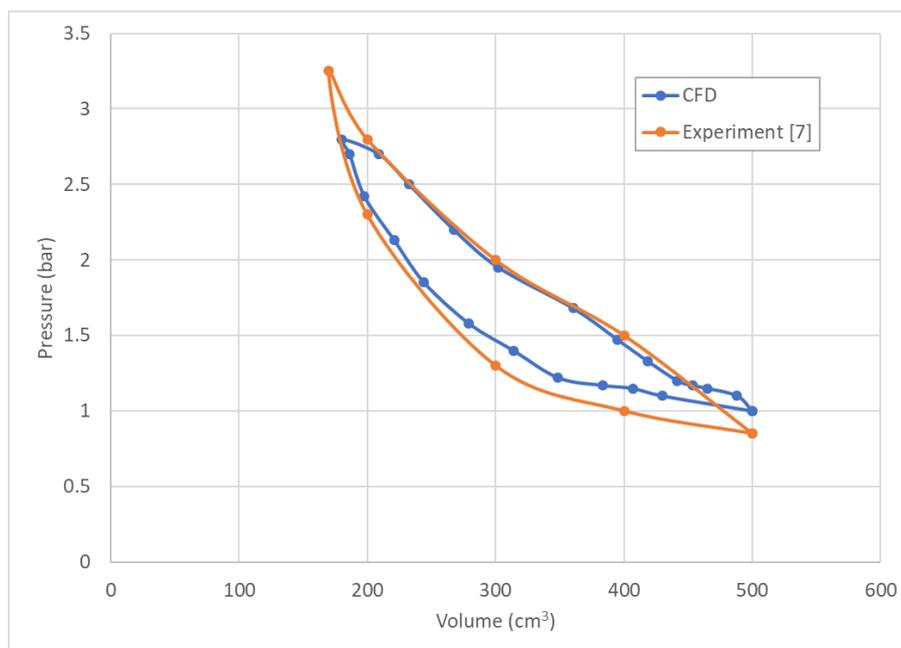
### 3. Results

#### 3.1 Model Validation

This section discusses the results of Stirling engine validation. The model is validated by comparing the simulation results obtained from this study with the experimental results that were obtained in [14]. Fig. 6. shows the comparison of pressure-volume relation of experimental result and CFD result obtained from this study. The pressure value is taken from the pressure in the cold volume every time step of the engine cycle. While the volume is the area of the displacer surface and the height of cold volume in every time step. From this result, the work done by the system can be derived by integrating the area of this p-V diagram according to the equation (8) stated below [15].

$$W_{out} = \frac{\omega}{2\pi} \sum_{i=1}^N 0.5(p_{i-1} + p_i) \cdot (V_i - V_{i-1}) \quad (8)$$

It has shown that the work done by this system in experiment is 18.4J while CFD result shows that the work done is 17.0J. This result shows a 4.3% of deviation of the numerical modelling from the real process. Although the comparison result shows a small deviation, as the preliminary result, it can be further improved and exploited in order to determine the best method for the heat transfer in Stirling engine especially from the heat source into the top volume of the Stirling engine.



**Fig. 6.** Volume and Pressure relation between experiment and CFD

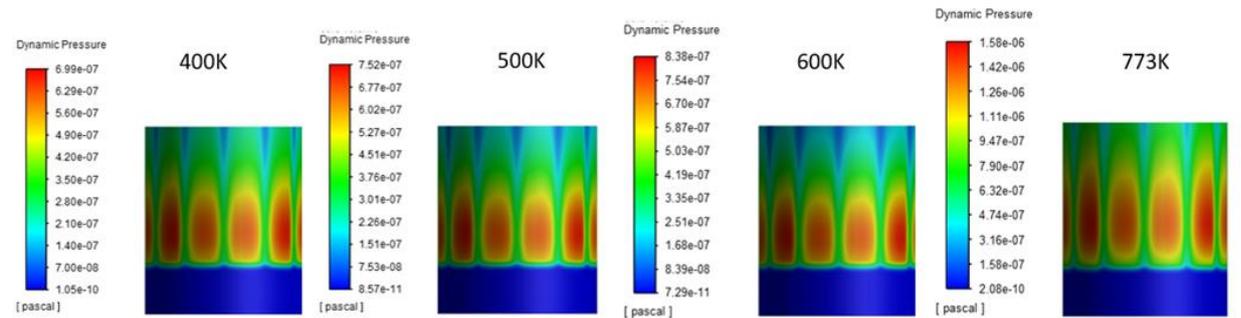
#### 3.2 Lower Temperature of Heat Source

##### 3.2.1 P-V diagram

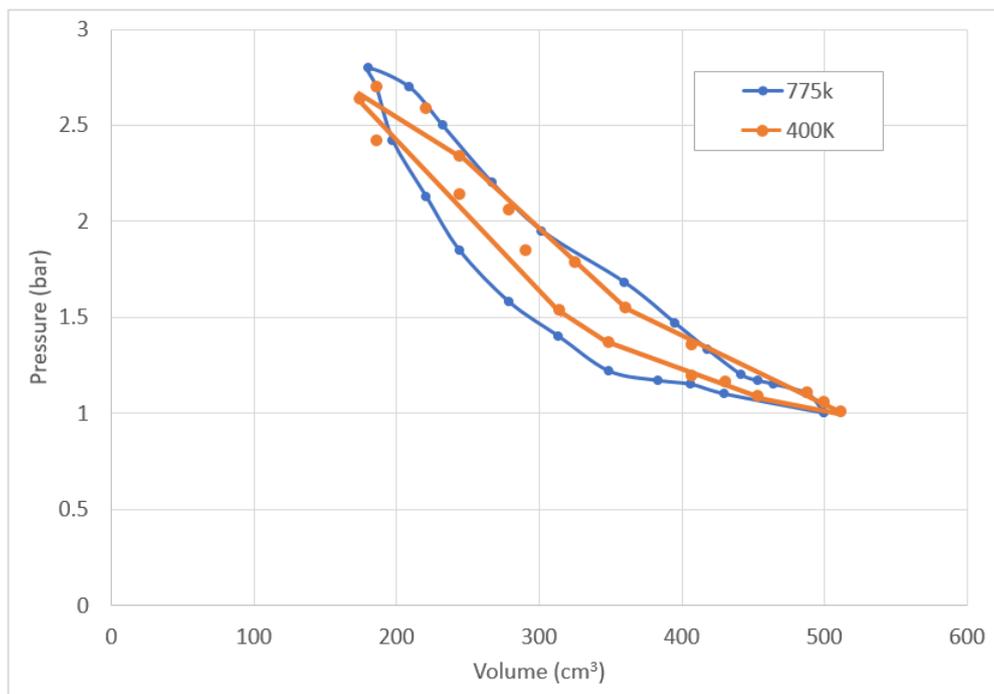
From the validated model, the simulations for the lower temperature of heat sources have been conducted to study the effect of low temperature of heat source to the work done of the engine. Volume and pressure in cold volume is taken into consideration to calculate the work done. Three value of heat source temperature were tested which are 600K, 500K and 400K. These values then were compared to see the dynamic pressure pattern in every temperature. The dynamic pressure pattern for each low temperature in Fig. 7. shows that the dynamic pressure decreases along when lower temperature is connected as the heat source at the top of the hot volume. The dynamic

pressure is taken into consideration because it shows how the working fluid flows in the cold volume with certain velocities under different temperature.

However, for the work done of the engine, temperature of 775K is compared with the lowest temperature tested 400K to see the possibility of using heat source temperature as low as 400K. Result in Fig. 8 shows that when the heat source is 775K, the work done by the engine is 17.0J, when the heat source is 400K, the work done by the engine is 10.4J. It shows the relation of the lower the heat source temperature, the lower the pressure in the cold volume which leads to a lower work done by the engine. Despite that some point is scattered, the trend of the volume and power of the cycle is same. Uneven curve shape of 400K p-v diagram is assumed related to the mesh or grid quality in the computational analysis, especially in the narrow gap between the wall and the displacer.



**Fig. 7.** Dynamic pressure distribution in cold volume of the cylinder engine for every temperature



**Fig. 8.** Volume and Pressure relation between heat source temperature 400K and 775K

From thermodynamic laws of energy in equation (9), energy of a cycle depends on pressure and volume, whereas when the pressure and volume change, the output power of engine will also change. Temperature of hot side of engine causes pressure to rise and pushes the piston move down, piston's moving down changes volume thus it makes total temperature and total pressure inside cylinder that

forces engine to run.  $T_c$  and  $T_H$  is temperature in cold volume and hot volume,  $R$  is the ideal gas constant. CR is the compression ratio of the engine.

$$W_{Total} = T_c R \left( \ln \left( \frac{1}{CR} \right) \right) + RT_H (\ln(CR)) \quad (9)$$

The bigger the temperature difference between hot and cold ends, the bigger work output can be obtained from the engine. So, it is important to optimize the heat transfer from the heat source to the hot volume of the cylinder to maximize the work done of the engine in lower temperature heat source.

#### 4. Conclusions

The simulation data of Stirling engine model is presented here. This paper has introduced a heat transfer enhancement method of Stirling engine that is useful for the waste heat recovery system that can benefit in reducing the reliance on fossil fuel. The CFD result from the p-V diagram indicates that the work done by this system is 17.0J which is 4.3% deviated from the work done obtained from the experimental result. From the validated model, it is compared with the lowest temperature tested 400K to see the possibility of using heat source temperature as low as 400K. Result shows that when the temperature is 400K, the work done by the engine is 10.6J. It can be understood that the lower the temperature of heat source, the lower the work done by the engine. The heat transfer from the heat source to the hot volume affect the pressure and volume of the cold volume, hence, affect work done and power output of the engine.

Since an uneven curve is obtained in p-v diagram of 400K heat source, further analysis on the grid or mesh sensitivity test should be conducted to quantify the influence of the mesh resolution on the solution and to analyse the optimum mesh that will produces high accuracy in the computational work. This study can be further improved and exploited in order to determine the best method for the heat transfer in Stirling engine as the waste heat recovery system in low temperature heat source applications such as domestic water heating, co-firing of pulverized biomass and industrial boilers. The development of the Stirling engine in the waste heat recovery technology will gives advantages in reducing the usage of the fossil fuel to generate power consumption which will lead to lower fuel used and ultimately the CO<sub>2</sub> emissions will be decreased. It is also can reduce the operational cost if the exhausted heat from the industrials can be recovered.

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